Robust Nitrogen oxide/Ammonia Sensors for Vehicle on-board Emissions Control

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(NNSA Minority Serving Institutes Program)

Los Alamos National Laboratory
June 11th 2015

This presentation does not contain any proprietary, confidential, or otherwise restricted information

Project ID: ACE079



Project Overview

Timeline

- Project Start Date
 - October 2012
- Project End Date
 - September 2015
- Percent Complete
 - 86%

Budget

- Total project funding
 - -3 Years : \$1,050,000
 - -DOE Cost : \$1,050,000
 - Cost Share : None
- Funding:Received in FY 15 \$ 350kFor FY 16 \$ 0k

Barriers

NO_x sensors that meet stringent vehicle requirements are not available:

- a) Cost (Complex sensors compared to the automotive λ sensor)
- b) Sensitivity (Need ± 5ppm or better sensitivity)
- c) Stability (Need ≈ 5000 hours)
- d) Interference (P_{O2}, P_{H2O}, hydrocarbons)
- e) Response time (< 1 sec)

Partners

- LANL Project Lead, Design, Testing
- ESL ElectroScience Sensor prototype manufacturer
- Custom Sensor Solutions, Inc Sensor electronics developer
- Washington State University Pulse Discharge Technique
- ORNL National Transportation Research Center. No cost.
 Funded directly by VT
- Rutgers University (no cost) –Signal processing
- Zircoa Corporation (NDA/MTA)



Relevance

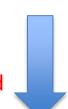
- From VT Program MYPP 2011-2015
 - Table 2.3-3 Tasks for Combustion and Emission Control R&D
 - Task 3. Engine Technologies R&D (fuel systems, sensors and controls, integrated systems, etc.)
 - Develop and validate NO_X and PM sensors for engine and after-treatment control and diagnostics
 - GOAL: By 2013, develop NO_x sensor materials and prototypic NO_x sensors that meet the sensitivity requirements identified by industry for emissions control in light duty diesel engines.
- Objective of the project is to develop low cost robust nitrogen oxide/ammonia sensors
- Accurate fast and reliable sensors can:
 - Improve efficiency of emissions system
 - Verification of emissions—system efficiency
 - Help validate models for the degradation of exhaust after treatment system
 - Potential feedback for effective engine control

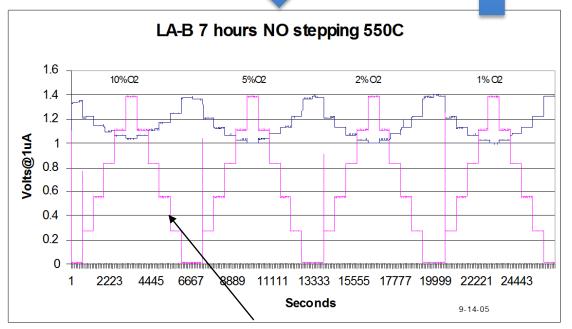


Approach (Previous Project)



Excellent performance of bulk sensor achieved





NO Mass flow controller



50 mm

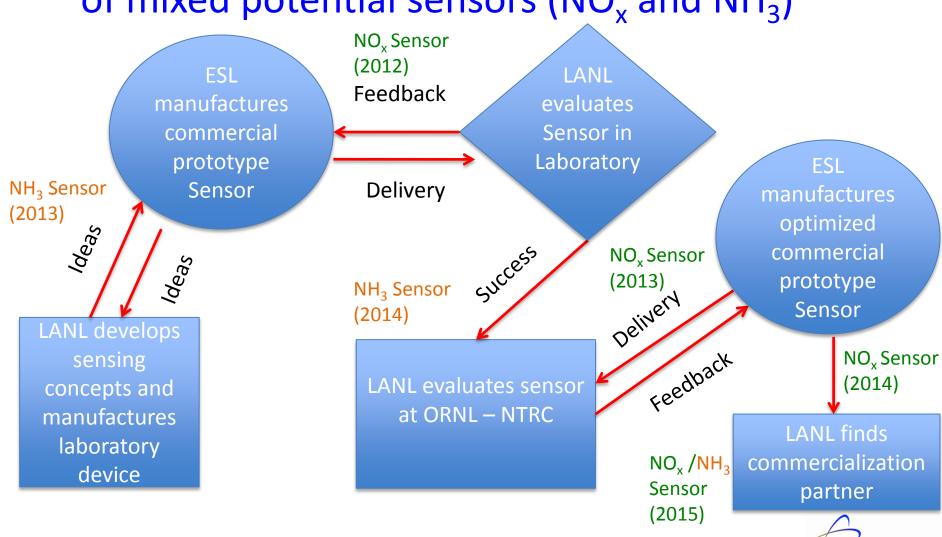
Need to retain performance in a commercially manufacturable device, validate, and transfer technology to industry

Data obtained by FORD Motor Co. R. Novak, R. Soltis, D. Kubinski, E. Murray and J. Visser September 2005



Approach

 Solve key issues impeding commercialization of mixed potential sensors (NO_x and NH₃)



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Approach - Milestones

- Milestone 1 (Dec 2014): Demonstrate NH₃ sensor response in an engine equipped with a simulated SCR system. (Complete)
- Milestone 2 (March 2015): Complete evaluation of Sulfur tolerance of NO_x sensor. (Complete)
- Milestone 3 (June 2015): Complete 3-electrode button cell studies on thee different perovskite electrode compositions. (Initiated: On track)
- Milestone 4 (Sept 2015): Demonstrate improved sensor selectivity by use of a catalytic layer on the overcoat of a NO_x sensor. (Initiated: On track)





NO_x/HC Sensor - Engine Evaluations

2014 AMR

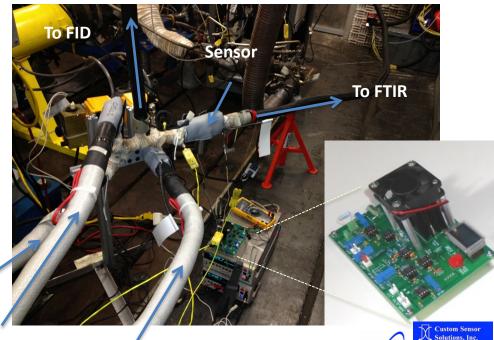
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- ✓ 1st Campaign: March 2013.
 - Primary focus, evaluati NO_x response, sensor control electronics, data acquisition system, and sensor packaging
- ✓ 2nd Campaign: January 2014.
 - Sensor in gas stream (flow restrictor removed)
 - Repeat NO_x, EGR experiments from Round 1 with improved sensor packaging
 - Stainless steel cap / internal shield
 - Perform cold-start experiments
 - Capture NO_x (post-DOC) and HC (post-DOC and engine out) data sampling configurations
 - Acquire data from sensor power supplies to understand behavior of sensor control systems
 - Heater voltage with simultaneous measurement of heater current to provide real-time data on sensor heater resistance and therefore sensor temperature
 - Perform EGR sweep experiments in NO_x and HC modes

GM 1.9L CIDI Engine

DOC out







HC/NO_x/NH₃ Sensor - Engine Evaluations

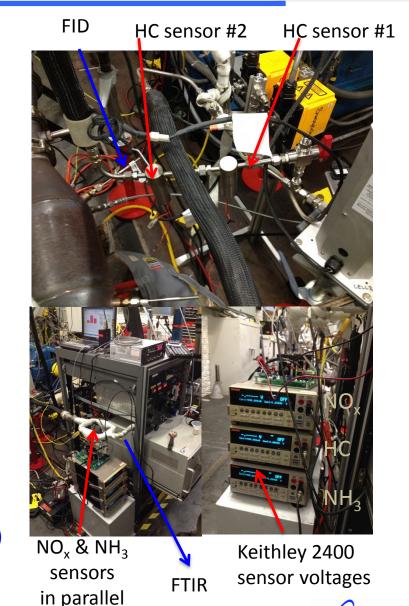
Technical Accomplishments

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✓ 3rd Campaign: March 2015.

- Simultaneous evaluation of NO_x, HC, and NH₃ sensors w/o attempting to repeat dyno runs.
- Added 4th (HC) to measure impedance of YSZ electrolyte to measure how well heater resistance feedback and power supplies fix operating T.
- Start-up: collected HC, NO_x, and NH₃ data before and after TWC.
- Vary engine load when operating in lean homogeneous and lean stratified operation.
- Lambda sweeps (0.98< λ <1.8) to determine characteristics of individual sensors over large changes in background PO₂.
- Inject known concentrations of NH₃ from bottle post TWC and upstream of NH₃ and NO_x sensors during lean operation (PO₂>5%) to simulate slip events from SCR.

BMW 120i GDI Engine



HC Sensor: Pt//YSZ//LSCO

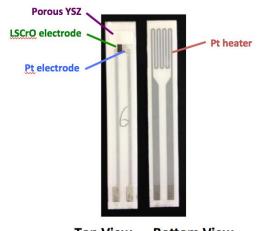
Operation @ 0 bias

NO_x Sensor: Pt//YSZ//LSCO

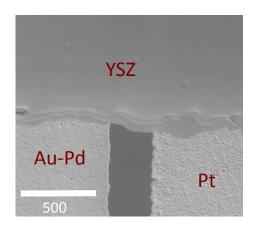
Operation @ +ve current bias

NH₃ Sensor: Pt//YSZ//Au

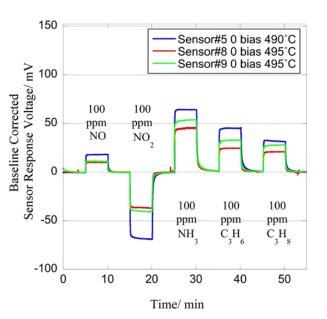
Operation @ 0 bias

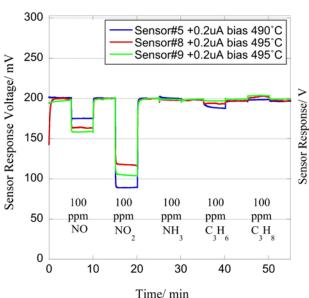


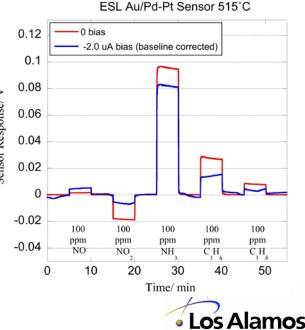




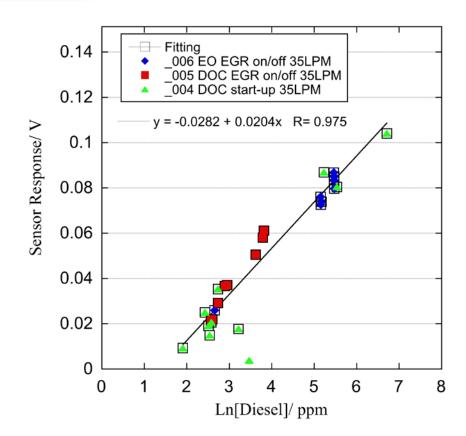
Potential to combine all 3 on one stick sensor





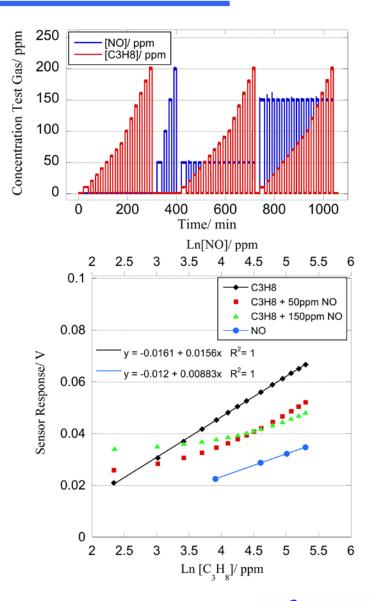


HC Sensor – Calibration



- ✓ Sensor quantitatively tracks total HC concentration
- ✓ Higher slope obtained in engine evaluations than lab calibration

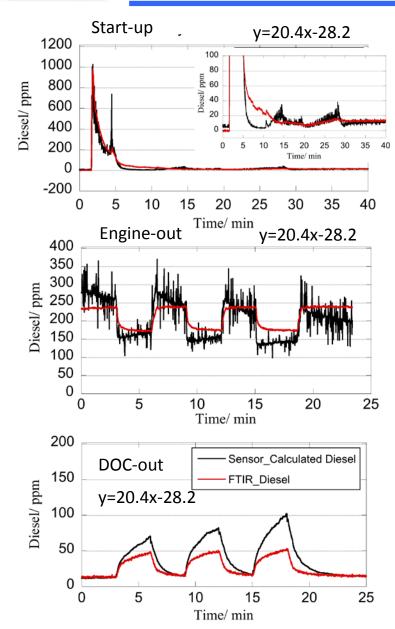
Sensor responding to higher order hydrocarbons (tracks total carbon in exhaust gas)







HC Sensor Performance



- Transients in HC content tracked by sensor voltage response.
- When sensor is sampling Engine-out exhaust, response is noisy. Calculated Diesel concentration from sensor response ±40ppm FTIR measurement.
- DOC out sensor signal less noisy, but sensor over predicts Diesel content by as much 50ppm compared to FTIR measurement.
- Issues to be resolved
 - Change in HC speciation as exhaust gas transports to instruments?
 - Non- trivial influence of interferent species?

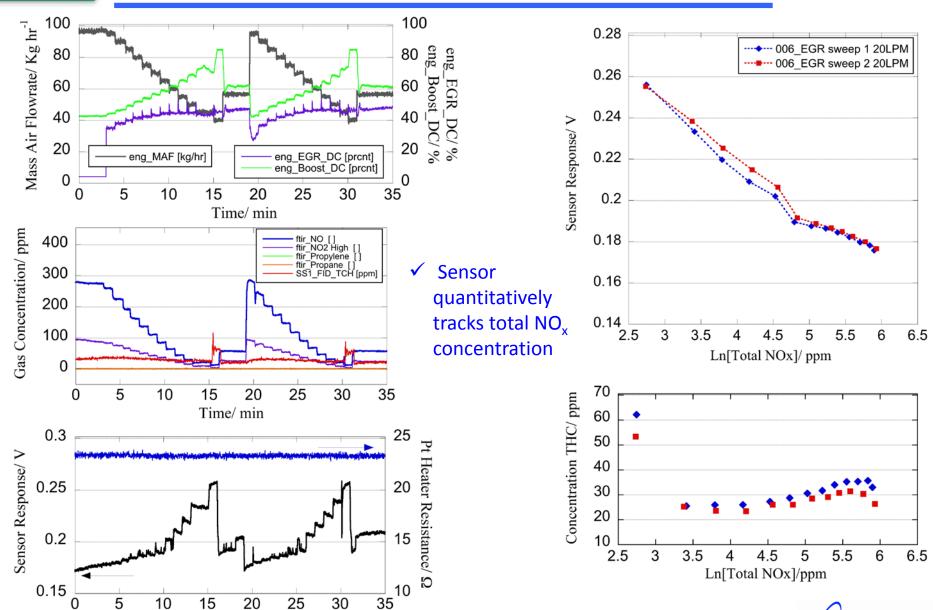




NO_x Sensor – Step EGR

2014 AMR

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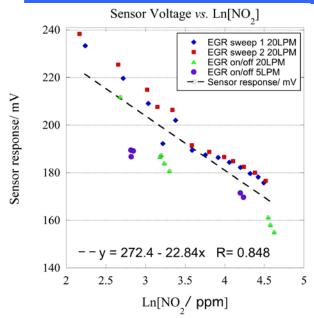
2015 U.S. DOE VT Program AMR and Peer Review Evaluation Meeting: June 11th, 2015

Time/ min

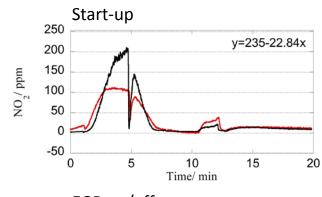


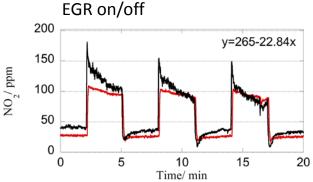
NO_x Sensor performance (CIDI)

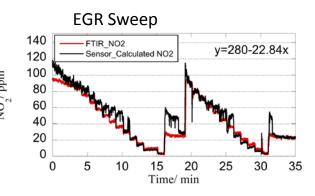
Technical Accomplishments



- Calibration curve used for comparing sensor voltage response to concentration of NO₂ only.
- Sensor voltage response during start-up appears to primarily track NO₂.
- For EGR on/off and sweep experiments, concentration calculated sensor response voltage is equally comparable to both NO+NO₂ and NO₂ only (when using the respective calibration curves).
- Y-intercept likely correlated to [THC] or other interferents but not in trivial (linear) way.







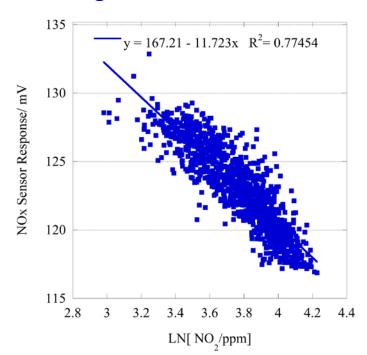


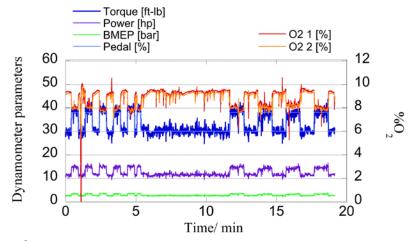


NO_x Sensor performance (GDI)

First test of NO_x sensor with overcoat in dynamometer

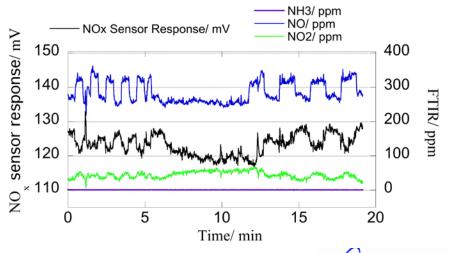
- Sensor tracks NO₂ concentration from FTIR
 - Good fit over all NO₂ concentrations
 - Insensitive to varying P_{O2}, P_{H2O} and hydrocarbons
- Improved sensitivity/selectivity can result in tighter calibration





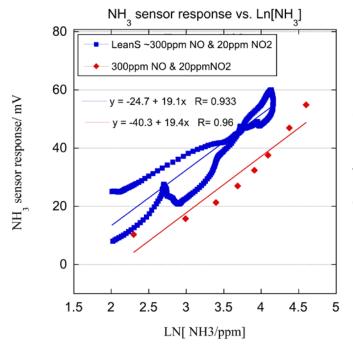
λ: 1.86-1.62

Vary load

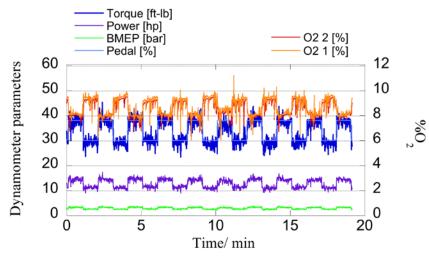


NH₃ sensor successfully tested in dynamometer for first time

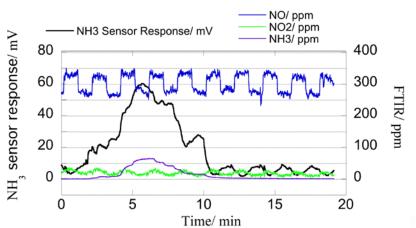
- Sensor tracks NH₃ injected after 3-way catalyst
 - Calibration under dry gases in lab over estimates concentration
 - Further tests underway to obtain appropriate calibration curve



Compare Dyno data with lab calibration



Engine in lean-stratified mode, vary load Inject NH₃ into exhaust stream post TWC

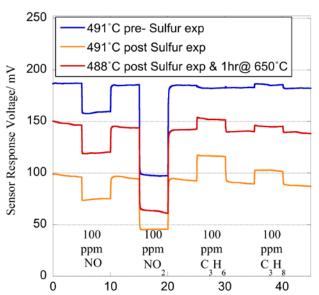


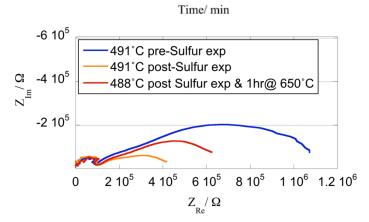




Sensor Tolerance to Impurities







Engineering Specification (ES)

- Sensor response to 100 ppm each NO, NO_2 , C_3H_6 and C_3H_8 in $10\%O_2$, $10\%H_2O$, balance N_2 measured before and after sulfur exposure
- Impurities testing conditions:
 - Sensor held at 500°C
 - 50 hour exposure to: $100ppm H_2S$ $1000 ppm SO_2$ $10\%H_2O$ $10\% CO_2$ balance N_2

No O₂ present during this test. Sensor not designed to operate under rich conditions for extended periods of time

- Sensor response measured immediately after sulfur exposure was suppressed relative to initial response
- After "clean-up" heat treatment, sensor response approached initial, pre-exposure response.
- Shorter heat treatment at higher temperature likely to recover initial sensor response.

MILESTONE 2



Test-

gas out

Potentiostat

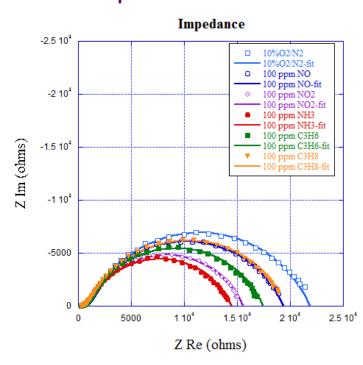
Outer gas chamber

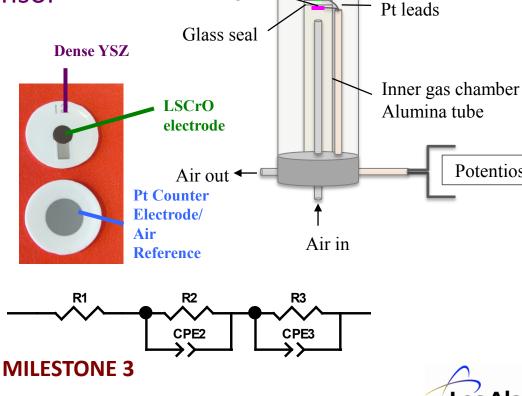
Quartz tube

Test-gas in

- **Electrode optimization**
 - Utilize 3-electrode setup
 - **Extensive Impedance Spectroscope**

Optimized compositions to be incorporated into stick sensor





WE

CE

Electrolyte

- Incorporate catalyst on top of protective overcoat
 - Catalyst has potential to optimize selectivity
- Preliminary results indicate that catalyst needs optimization

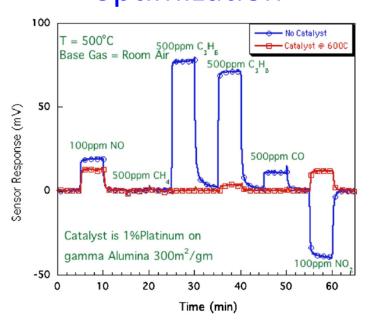
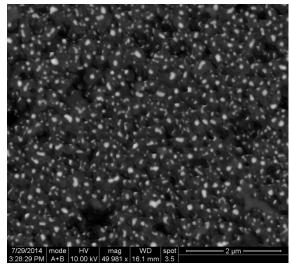


Figure 1. (Color online) Selectivity of a Pt/YSZ/La $_{0.8}$ Sr $_{0.2}$ CrO $_3$ sensor with and without a Pt/ γ -Al $_2$ O $_3$ catalyst.

2

Left to Right: Non-Overcoat, Overcoat, Pt Catalyst.



SEM image showing isolated Pt- particles (white) on top of porous alumina overcoat (black)

Electrochemical and Solid-State Letters, 10 (2) J26-J29 (2007) 1099-0062/2006/10(2)/J26/4/\$20.00 © The Electrochemical Society

MILESTONE 4



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- NDA/MTA being negotiated with Continental, Ford, Chrysler and SWRI® to ship sensor systems for evaluation. Provided information to Delphi.
- LANL issued a broad Call for Commercialization Partners (RFI/RFP)
 - Released on 11/7/14 to 45 companies; Call closed on 12/8/14
 - Received 5 Letters of Interest from a variety of OEMs, Tier 1 suppliers and sensor development companies

LANL Webinar

- Successful interaction with 5 potential commercialization partners on Jan 28th, 2015
- Presentations shared with all the participants
- 1 company expressed interest in further evaluating sensors at their test facility under NDA/MTA
- Several companies submitted "Product Commercialization Plans" by the Feb 25th deadline
- LANL selected one company and is currently negotiating a license and potential CRADA for additional collaborative development to accelerate time to market.
- Commercialization of promising technologies takes time:
 - The real need for a low cost robust NO_x sensor technology presents ideal timing for a successful Lab-Industry partnership
 - Packaging may involve further sensor modifications/development.
 - Further improvements in sensitivity and selectivity would increase the probability of successful commercial deployment of this technology. Calibration under dynamometer conditions needs to be more robust.

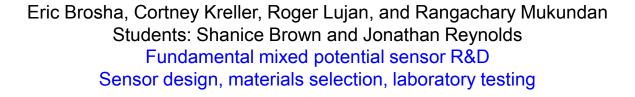
Responses to Previous Year Reviewers' Comments

- The development of low cost, robust, and accurate NO/NH₃ sensors would help improve efficiency and lower emissions. The reviewer commented that it would help validate models for the degradation of exhaust after treatment system, and would help develop better engine controls. The reviewer said that sensors are currently expensive. This person further noted only one supplier of NO_x sensors and possibly two suppliers of NH₃ sensors, and noted that these sensors are critical to high-efficiency closed loop control and OBD.
 - This project has developed the technology to a level where Tier I suppliers/OEMs are interested. In the future, expand the use of these sensors to model validation and develop better engine controls in collaboration with ORNL.
- The reviewer commended that the project had made very good progress. However, according to the reviewer engine results are troubling. The scatter is 150 to 400 ppm diesel at approximately 80mv response. The best plots are response to concentration. Time plots are only useful for time response, not for concentration response.
 - Have used various calibrations to provide quantitative comparison of sensor response and gas concentration in engine dynamometer. The future work is geared to improving the sensor sensitivity/selectivity by optimizing electrode composition and incorporating heterogeneous catalysts.
- The reviewer found that the project appeared to have engaged university, national laboratory, and industry partners effectively and was commended for actively seeking commercialization paths for this innovative technology. The reviewer suggested that a <u>real sensor manufacturer needed to be recruited</u>. The reviewer suggested that next must be <u>OEM or Tier 1 automotive manufacturer input</u> to confirm requirements and critique of implementation to significantly improve the product development speed and final result. The reviewer observed good initial work to get stable linear output, and, as mentioned above, improving the full range signal would likely require on-sensor electronics development and continued engine testing for sensor stability. The reviewer concluded that the current budget did not appear to comprehend these activities in whole. The reviewer recommended an <u>OEM/Tier 1 partner</u> for additional funding.
 - Commercialization activities were initiated this FY and a Tier 1 supplier has been identified as a partner to further
 the development of these sensors. LANL will address improving sensor sensitivity/selectivity and work closely
 with sensor manufacturers to develop packaging.

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Collaboration







Ponnusamy Palanisamy Manufacturing, scale-up, valuable feed back in sensor design



Bill Penrose

Custom sensor control electronics: Heater control and High impedance boards



National Transportation Research Center Vitaly Y. Prikhodko, Josh A. Pihl, and James E. Parks II Sensor test site.

No Cost Partner Directly funded by VT





Washington State University (Praveen Sekhar) Zircoa (Boris Farber)

Utilizing PDT to improve sensor selectivity

Rutgers University (No cost) (Alexandre Morozov)

Licensing agreement with a Tier 1 supplier is under negotiation



Future Work

Optimize sensors

- Improve sensitivity/selectivity by selection of appropriate electrode compositions
- Improve selectivity by use of catalyst coating over sensor protective overcoat
- Work with Commercialization partner
 - Tier 1 supplier will lead commercialization efforts (Licensing agreement under negotiation)
 - ESL will work closely with Tier 1 supplier to transfer processing details
 - LANL will work closely with Tier 1 supplier to successfully transfer technology
 - Electronics package development
 - Extensive dyno evaluation
- Expand sensors to support EERE emission control research and development (collaboration with ORNL)
 - Provide inline (non-extractive) NO_x, HC, NH₃ sensing capability
 - Better evaluate engine control technology
 - Model validation



Summary

- Successfully transformed LANL patented mixed-potential sensor technology to a commercial manufacturing platform
 - HTCC process (ESL collaboration)
- Demonstrated capability of HC, NO_x and NH₃ sensors during engine dynamometer evaluations at ORNL NTRC
 - 1st campaign: qualitatively evaluate sensors and identify problems
 - 2nd campaign: quantify NO_x and HC sensors in CIDI engine
 - $-\,$ 3rd campaign: simultaneously quantify NO $_{\rm x}$, HC and NH $_{\rm 3}$ sensors in GDI engine
- Identified commercialization partner (Tier 1 supplier)
 - Licensing under negotiation
 - Will work closely with Tier 1 supplier and ESL to commercialize technology
- Improve sensor sensitivity and selectivity to facilitate calibration and signal processing
- Integrate sensors with dynamometer to provide gas composition data at various locations (non-extractive)



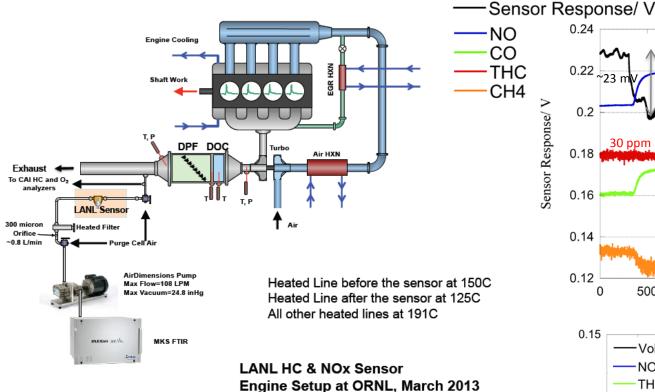
Technical Back-Up Slides



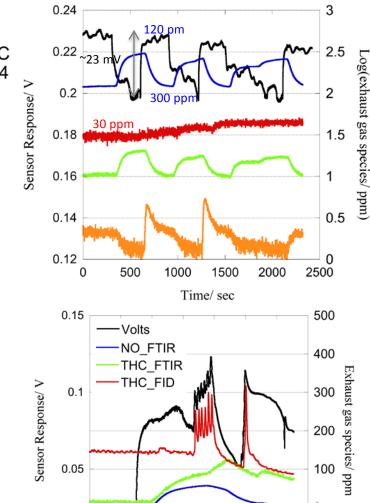


NO_x Sensor - Engine Evaluations

2013 AMR



- Test LANL sensors under realistic conditions
- Validate response with analysis equipment
- Identify potential issues with sensor
- Provide feedback to develop better sensors



100

200

300

400

Time/sec

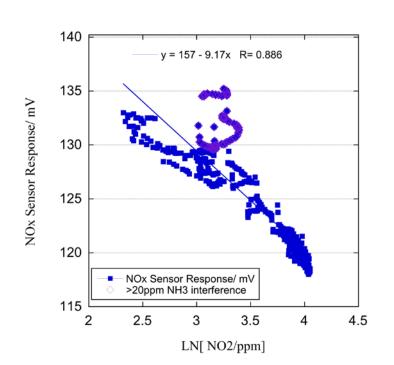
500

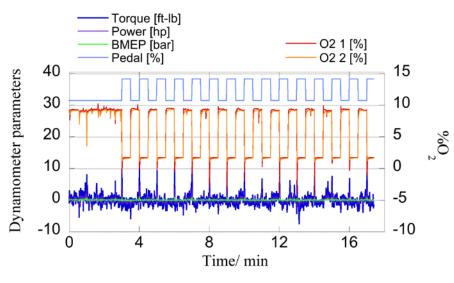
600

700

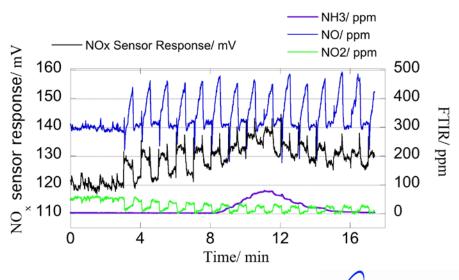
-100

- Sensor tracks NO₂ concentration from FTIR
 - Good fit over all NO₂ concentrations
 - Insensitive to varying P_{O2}, P_{H2O} and hydrocarbons
 - Interference from >20ppm NH₃





λ switching 1.1 \rightarrow 1.8



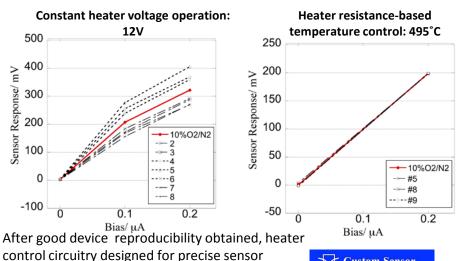


2nd generation ESL sensor: characteristics

ESL can prepare multiple devices as needed.

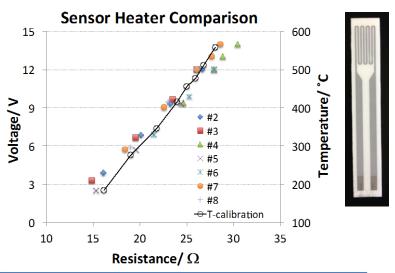


Response reproducibility 1st batch, 2nd gen

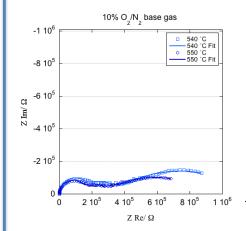


temperature control.

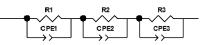
Sensor reproducibility - heater



Sensor impedance dominated by interfacial resistance as desired



	540 °C	550 °C
R1	1.41E+05	1.21E+05
CPE1-T	4.87E-11	5.19E-11
CPE1-P	1.05	1.04
R2	1.70E+05	1.42E+05
CPE2-T	1.43E-08	4.14E-08
CPE2-P	0.73	0.62
R3	8.67E+05	6.55E+05
CPE3-T	1.53E-06	1.93E-06
CPE3-P	0.39	0.38



Replicates LANL bulk devices!



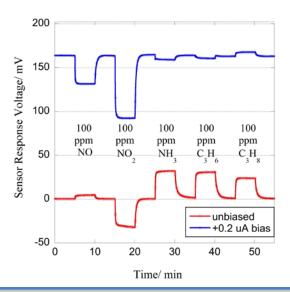
Custom Sensor

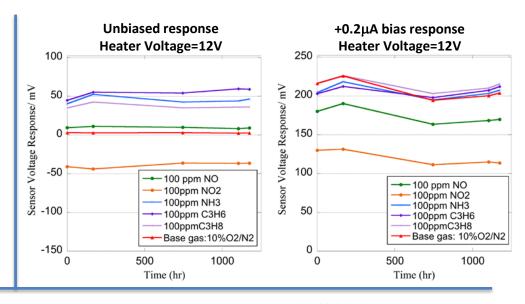
Solutions, Inc.

2nd generation ESL sensor: characteristics

Sensor response to application of current bias

Stability over 1000hr of testing





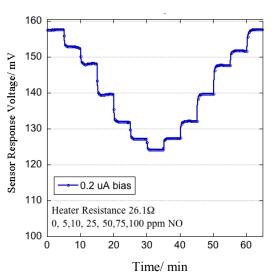
Effect of bias current application on NO response:

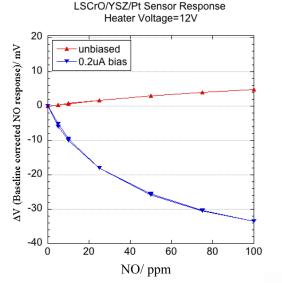
10 Heater Resistance 26.1Ω 0, 5,10, 25, 50,75,100 ppm NO

-- unbiased

2 0 10 20 30 40 50 60

Time/ min





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